



Feasibility analysis and development of on-road charging solutions for future electric vehicles

## Dynamic wireless charging for more efficient FEVs: The FABRIC project concept

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# Electromobility

- Electromobility or electric mobility or e-mobility is the propulsion of vehicles using electricity instead of conventional fuel.



# Why Electromobility? – Social benefits

## ○ Environmental benefits:

- Minimization of vehicle produced air pollutants
- Benefits increase with the cleanliness of the power production process
- RES-produced energy, consumed by EVs maximizes benefits

## ○ Societal benefits:

- Cleaner city air > better quality of life, reduction of hospitalizations
- Quieter vehicles

## ○ Large-scale economic benefits:

- Industrial and employment boost
- Reduction of climate change catastrophic phenomena, that cost billions

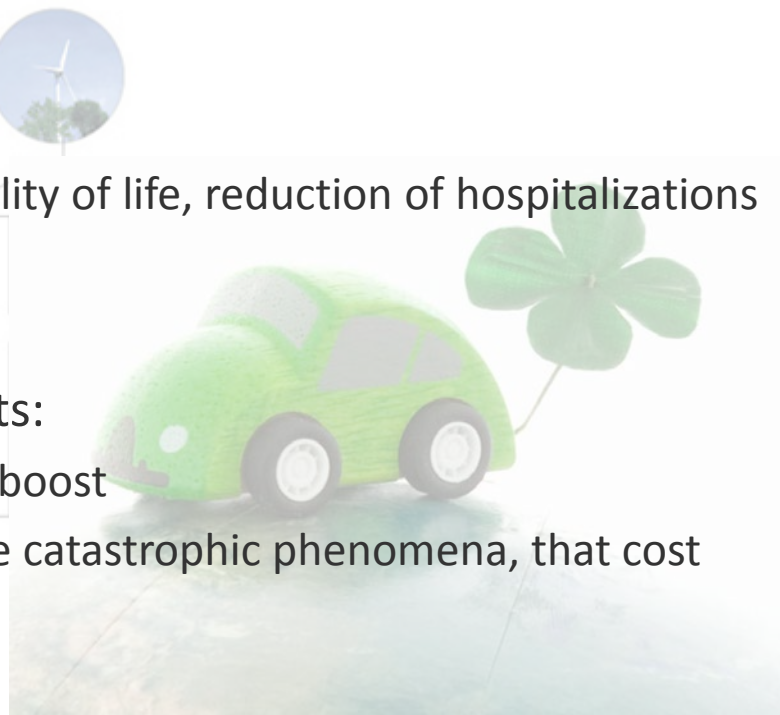
Electricity Sources

Wind

Solar

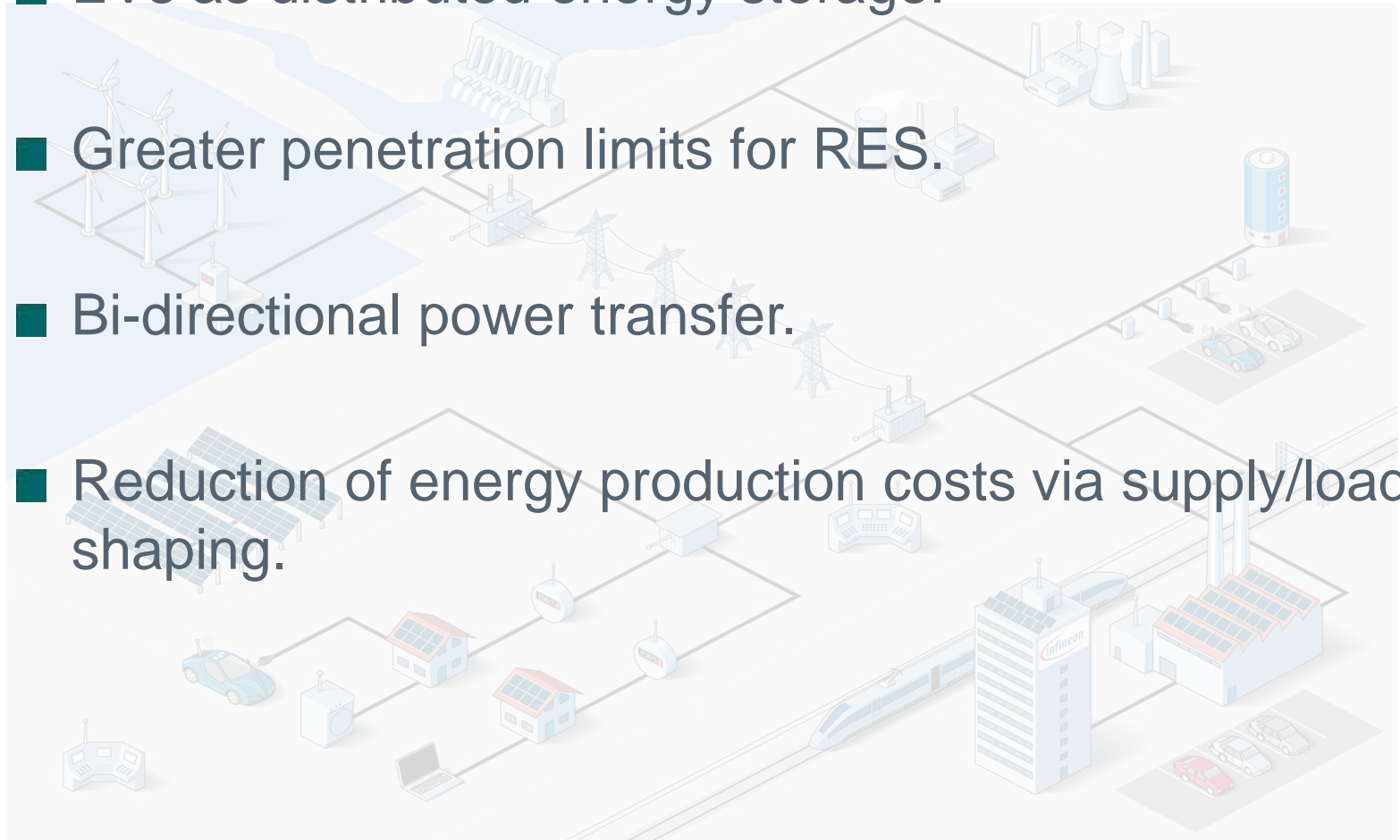
Electrical Grid

Water



# Why Electromobility? – Grid benefits

- EVs as distributed energy storage.
- Greater penetration limits for RES.
- Bi-directional power transfer.
- Reduction of energy production costs via supply/load shaping.



# Global initiatives towards electromobility

- **NORTH AMERICA**

- The US Transportation Electrification Program represents the world's largest EV demonstration project. \$400 million funding. Target: 1 million plug-in EVs by 2015. \$4 billion funding for clean transport research.

- **ASIA**

- China, Japan, Korea: government incentives, regulations promoting awareness and adoption of EVs.
- Toyota, Nissan, Honda, Mitsubishi joint development of charging infrastructure. Target: 8000 new normal chargers, 4000 new fast chargers.

- **EUROPE**

- 2013 European Parliament [resolution](#) requiring member states to install a specified number of EV charging stations and hydrogen and natural gas stations by 2020. Targets: Germany 86000, Italy 72000, UK minimum of 70000.
- Many EU funded R&D projects: EcoFEV, UNPLUGGED, FABRIC...
- Several national projects: Fastned (NL), ELMO (EE), CLEVER (DK)...

# Roadblocks for large scale electromobility adoption

EVs as percentage of the whole fleet:

- France 0.83%
- US 0.62% (96000 sold in 2013)
- Japan 0.59%
- Germany 0.25% (7400 sold in 2013)

Current penetration of EVs very small.

Reasons:

- Weight and size of batteries.
- Cost of battery manufacturing.
- EV price premium over conventional vehicles.
- Small or non-existent charging infrastructure network.
- Long duration of charging.
- Plugging the EV in is not a user friendly experience.



Solutions:

- ITS
- Novel charging technologies



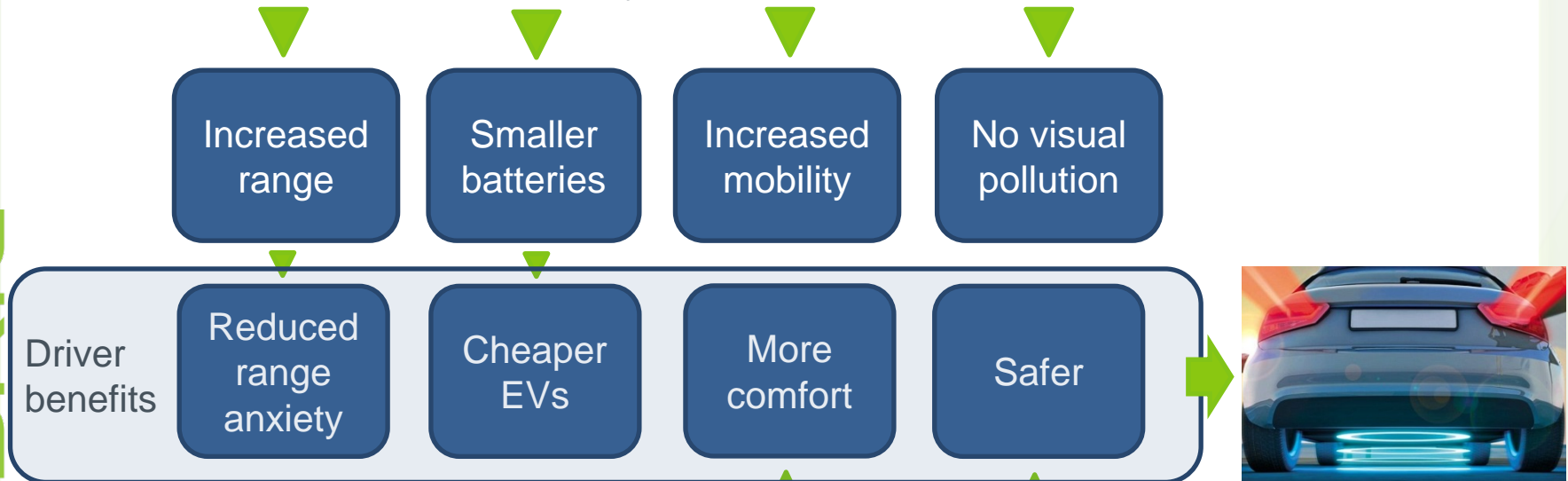
# ITS solutions facilitating electromobility

- Accurate range estimation.
- Robust travel planning.
- User convenience.
- Use of smaller batteries.
- New charging technologies (e.g. dynamic charging).



# Why wireless charging

- Allows EV charging while travelling (dynamic) or during short stops ideal for urban environment (stationary)



- Drivers do not have to deal with dirty and potentially dangerous cables (rain, cable vandalism, cable wear, etc) + Easier charging process



Roosegaarde and Heijmans

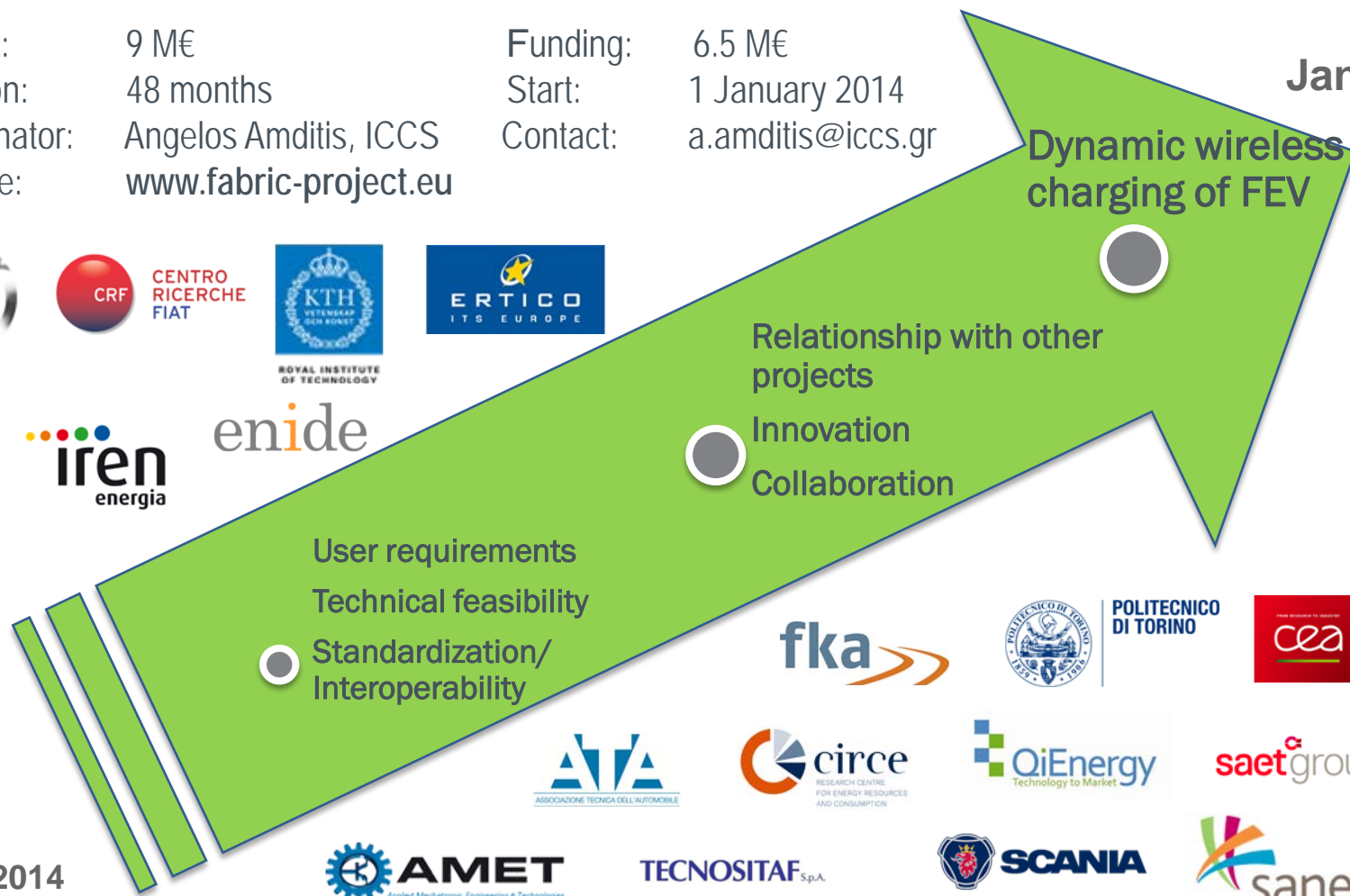


# FABRIC Integrated Project

Budget: 9 M€  
 Duration: 48 months  
 Coordinator: Angelos Amditis, ICCS  
 Website: [www.fabric-project.eu](http://www.fabric-project.eu)

Funding: 6.5 M€  
 Start: 1 January 2014  
 Contact: [a.amditis@iccs.gr](mailto:a.amditis@iccs.gr)

Jan 2018



Jan 2014



POLITECNICO DI TORINO



# EV charging modes (I)

## Static (now)

- Example application scenarios:
  - Car parking in a garage or car park.
  - Bus parking at a bus terminus or station.
  - Freight vehicles while loading or unloading.

Parameter	Range	Comments
Vehicle speed (km/h)	0	Mode applicable if stationary for longer than 5 minutes
Vehicle acceleration (m/s <sup>2</sup> )	N/A	
Transmitted power level range (kW)	3 to 50	
Power transmitted to which component	N/A	Power transmitted to the vehicle on-board energy storage system only
Charging time (minutes)	>5	Upper limit of charging time is subject to use, power rating and vehicle on-board energy storage system capacity
Vehicle status	N/A	Vehicle engine / power will generally be off during charging (but may be on for a short time while initiating coupling / charging process)

# EV charging modes (I)



Full battery recharging < 1hr

# EV charging modes (II)

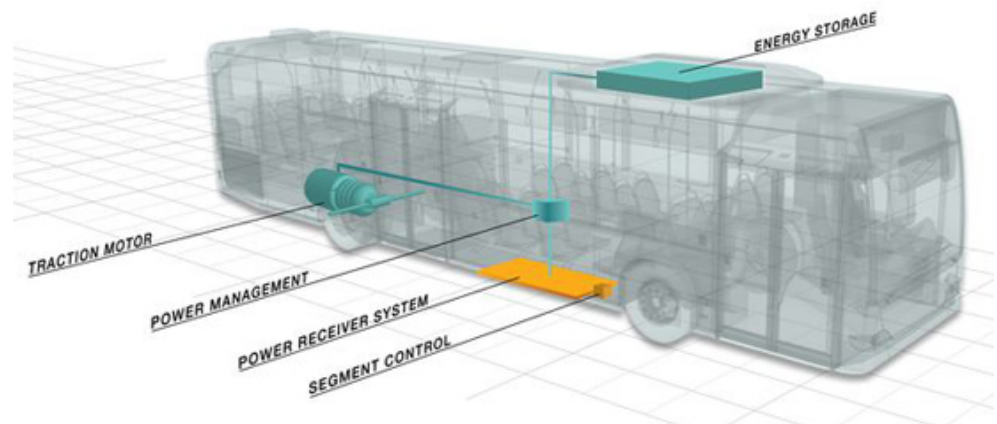
## Stationary (near future)

- Example application scenarios:
  - Taxis queuing in a taxi rank
  - Bus stopping at bus stops
  - Vehicles stopping at junctions, rail level crossings, etc...

Parameter	Range	Comments
Vehicle speed (km/h)	0	Mode applicable if stationary for less than 5 minutes
Vehicle acceleration (m/s <sup>2</sup> )	N/A	
Transmitted power level range (kW)	20 to 200	
Power transmitted to which component	N/A	Power transmitted to the vehicle on-board energy storage system only
Charging time (minutes)	<5	Upper limit of charging time is subject to use, power rating and vehicle on-board energy storage system capacity
Vehicle status	N/A	Vehicle engine / power can be on or off depending on the vehicle powertrain control and exact application

# EV charging modes (II)

Operational in Braunschweig,  
Germany since 2013  
200kW inductive stationary  
charging





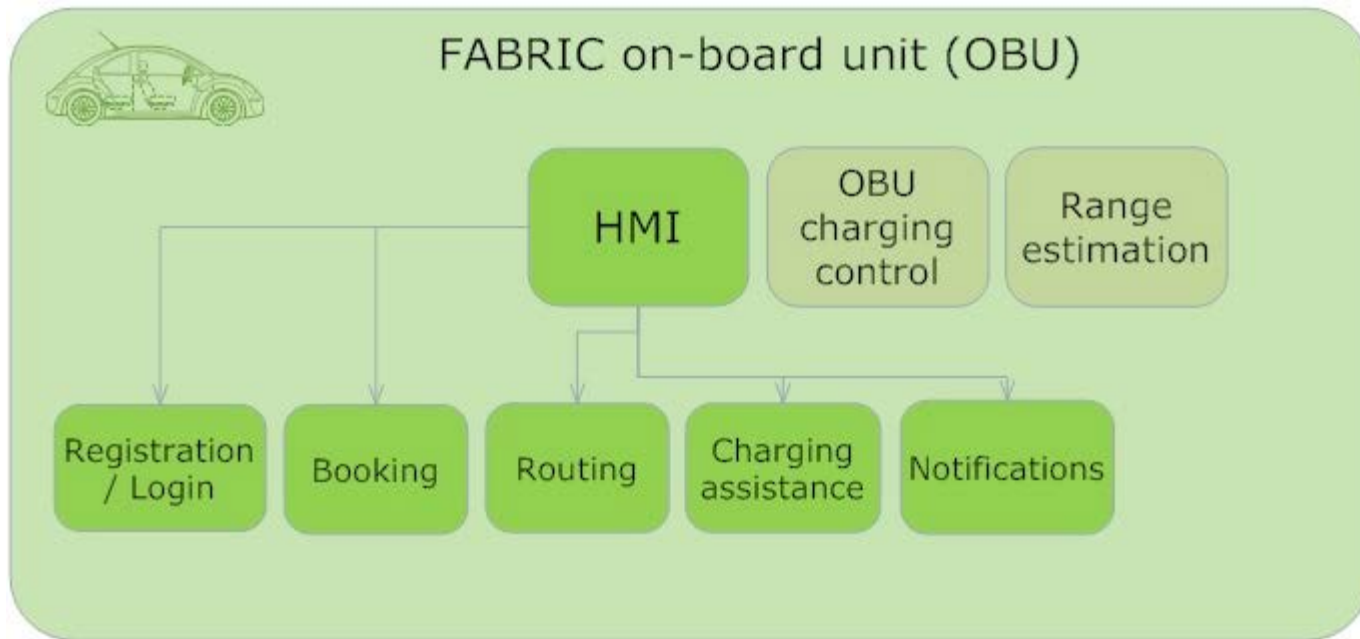
# EV charging modes (III)

## Dynamic (distant future)

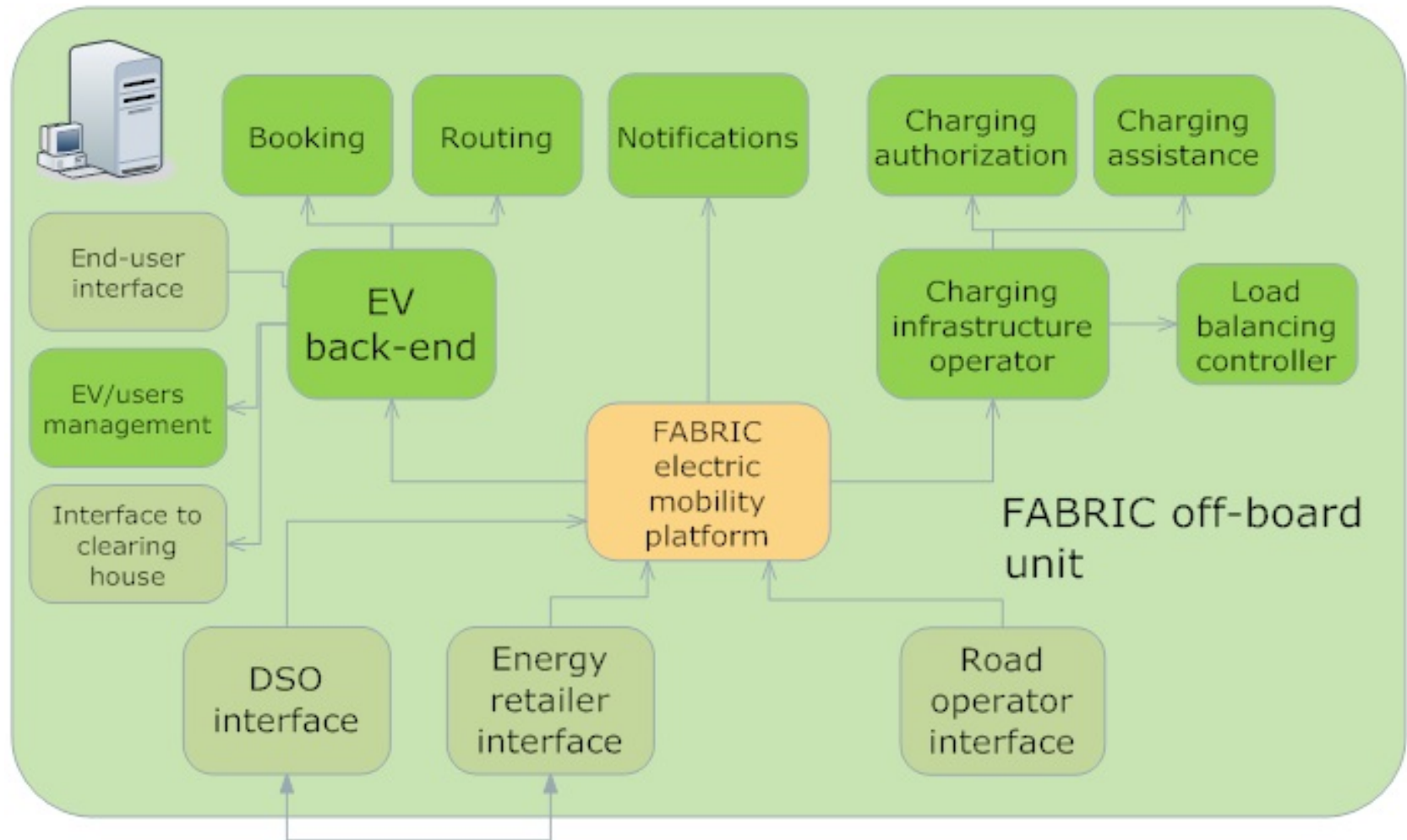
- Example application scenarios:
  - Highways (multiple lanes).
  - Urban roads with dedicated charging lanes.
  - Dedicated vehicle type, mode lanes.

Parameter	Range	Comments
Vehicle speed (km/h)	$0 < v < 130$	
Vehicle acceleration (m/s <sup>2</sup> )	-	Range covers possible accelerations of vehicles ranging from cars to trucks
Transmitted power level range (kW)	20 to 360	
Power transmitted to which component	N/A	Power transmitted either to the vehicle electric drive or, to the on-board energy storage system or, both
Charging time (minutes)	<5	Depends on vehicle speed and dimensions of the primary charging infrastructure.
Vehicle status	N/A	Vehicle engine / power is on during the power transfer process

# FABRIC preliminary ICT architecture (I)

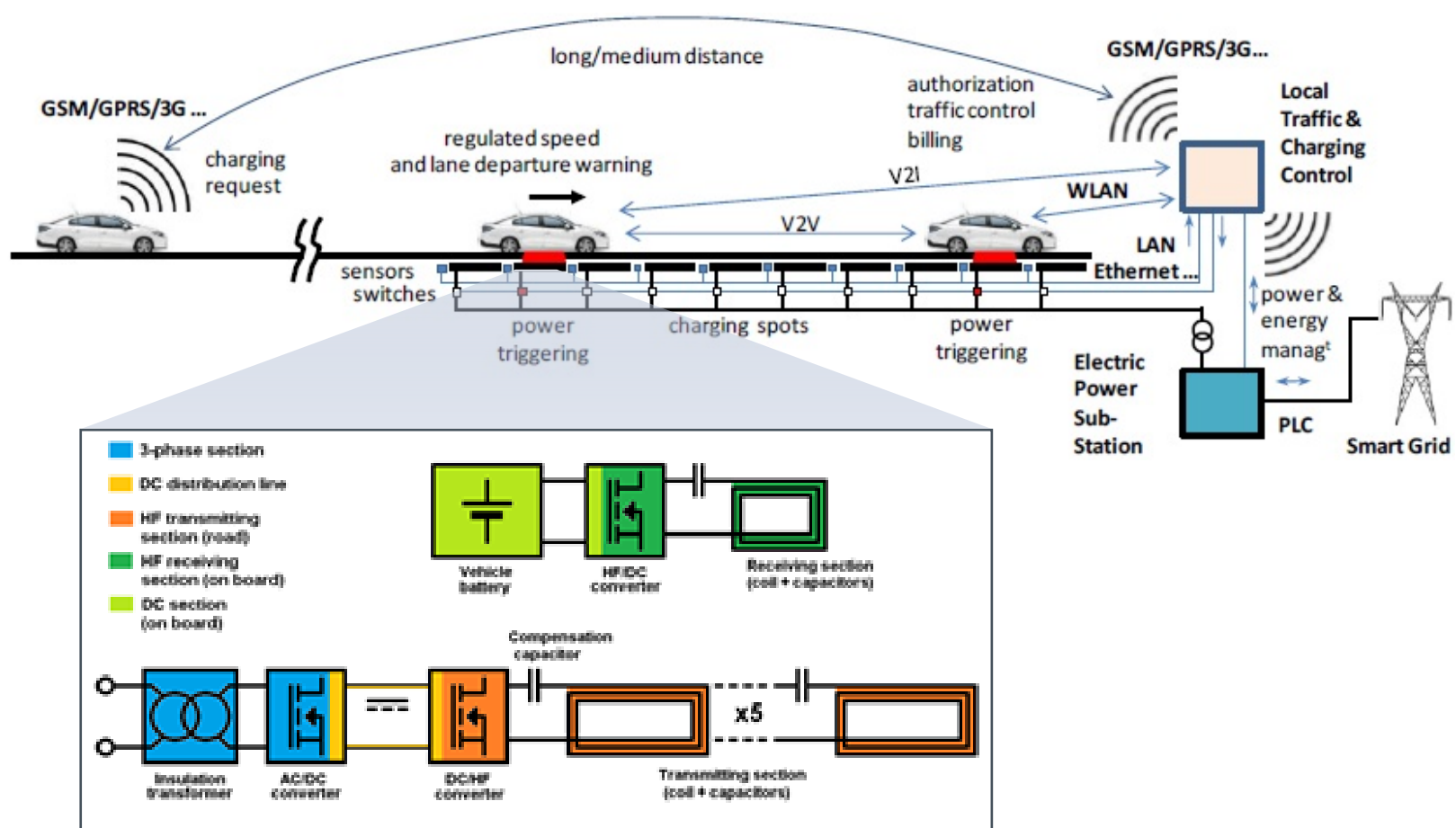


# FABRIC preliminary ICT architecture (II)



# FABRIC prototypes – POLITO, IT (I)

*Development of dynamic charging prototype no1 – Italy (POLITO, CRF)*  
- 200m test track, 20kW, ~150kHz



# FABRIC prototypes – SAET, IT (II)

*Development of dynamic charging prototype no2 – Italy (SAET)*

*– 50m, 10-150kHz load-resonant power frequency*

## Position 1

Vehicle detection & recharging system in stand-by



## Position 2

Vehicle is charging by passing over the recharging pad and receiving transmitted power



Transmitted power depends upon:  
- Speed  
- Power unit  
- Track length

## Position 3

Vehicle has been automatically recharged while driving.



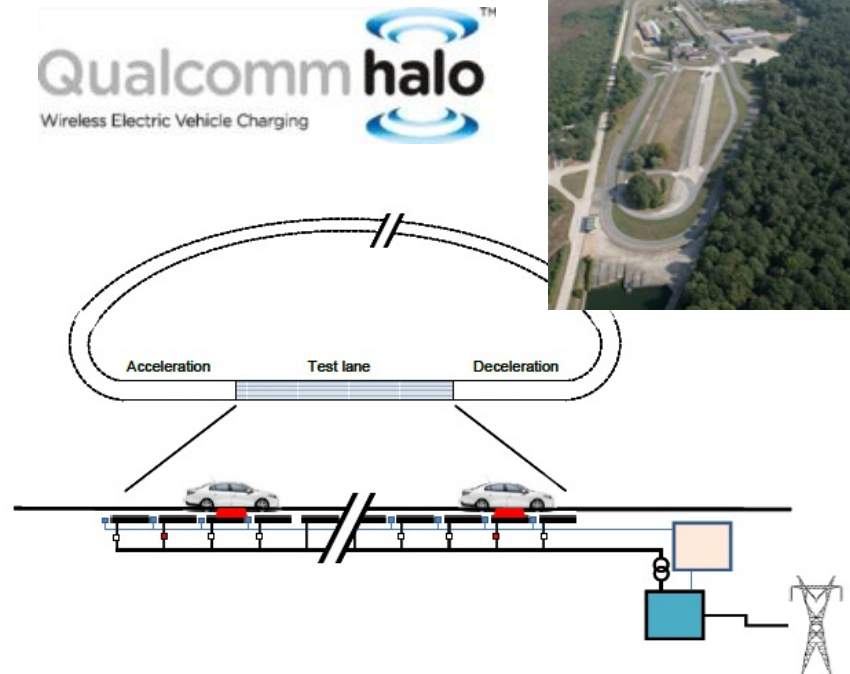
Source: SAET



# FABRIC prototypes – VEDECOM, FR (III)

## 3. Development of dynamic charging prototype no3 – France (QUALCOMM, VEDE ( IFSTTAR RENAULT PSA PEUGEOT CITROËN ifp Énergies nouvelles ParisTech INTempora ))

- 100m test track, QUALCOMM charging pads in series, 85kHz, >20kW





# Dynamic charging challenges (I) - Road

Road adaptation – electrification

- Initial investment
- Maintenance costs
- Lifecycle assessment
- Traffic impact assessment



# Dynamic charging challenges (II) - Grid

- **Increased demand**
  - RES penetration increase necessary
  - Investments on new base units
  - Incentives to charge during off-peak hours
    - Need for robust communication network with the end users
- **High frequency demand fluctuations**
  - Need for energy storage systems
    - Size, cost and feasibility assessment
- **Smart grid necessary**
  - Potential new security vulnerabilities



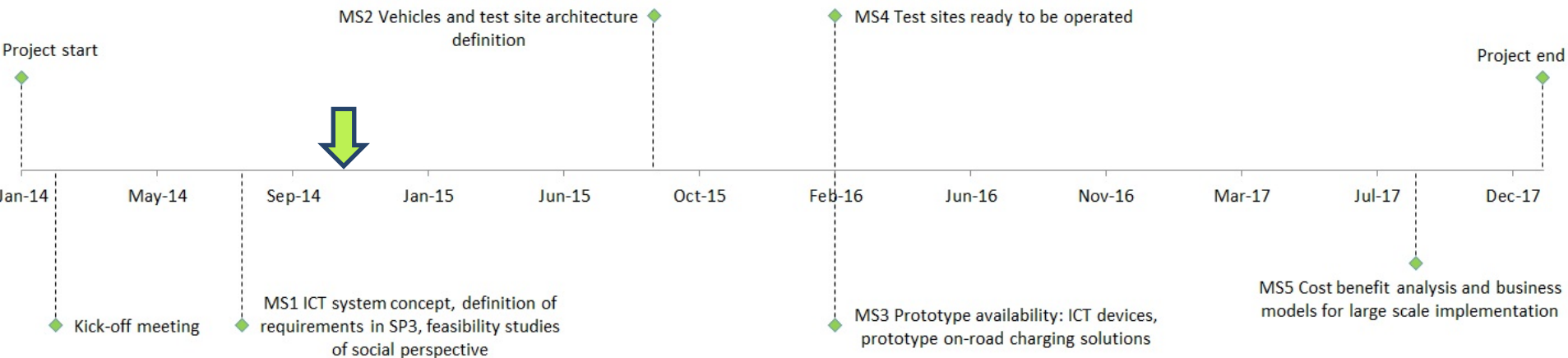


# Dynamic charging challenges (III) - ICT

- Need for fast (real time) V2I communications
- Real time load balancing and charging management
- Unobtrusive, non-distracting user interfaces



# FABRIC major milestones







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for future electric vehicles

# Thank you!



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